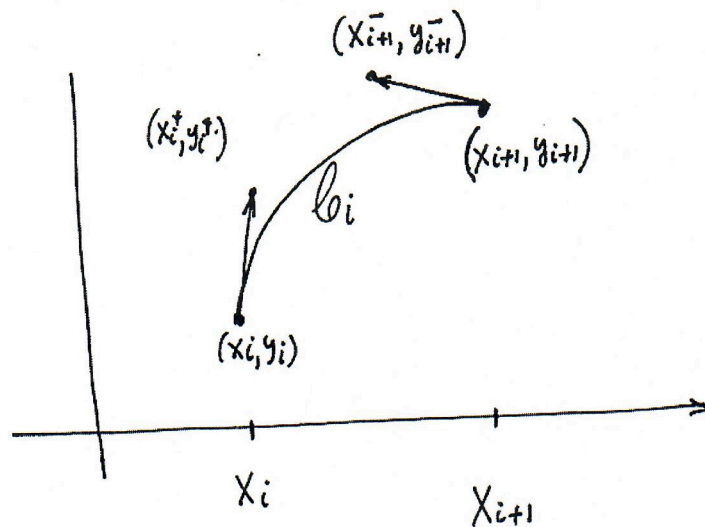


Bezier curves



Interpolation points are : $(x_i, y_i), (x_{i+1}, y_{i+1})$

Guidepoints are : $(x_i^+, y_i^+), (x_{i+1}^-, y_{i+1}^-)$

Hermite Polynomials for the parametric equations:

$$b_i: \begin{cases} x_i(t) = a_0^{(i)} + a_1^{(i)}t + a_2^{(i)}t^2 + a_3^{(i)}t^3 \\ y_i(t) = b_0^{(i)} + b_1^{(i)}t + b_2^{(i)}t^2 + b_3^{(i)}t^3 \end{cases} \quad t \in [0, 1] \quad (1)$$

They satisfy the following BCS :

$$x_i(0) = x_i$$

$$x_i(1) = x_{i+1}$$

$$x_i'(0) = x_i^+ - x_i$$

$$x_i'(1) = x_{i+1} - x_{i+1}^-$$

$$y_i(0) = y_i$$

$$y_i(1) = y_{i+1}$$

$$y_i'(0) = y_i^+ - y_i$$

$$y_i'(1) = y_{i+1} - y_{i+1}^-$$

(3)

(4)

(5)

(6)

by multiplying by a constant all the derivatives at the ends,* the slopes of the tangents to the curve C_i at (x_i, y_i) and (x_{i+1}, y_{i+1}) do not change. For Bezier curves, that constant is "3". It means

$$x_i'(0) = 3(x_i^+ - x_i) \quad , \quad y_i'(0) = (y_i^+ - y_i)3 \quad (5.2)$$

$$x_i'(1) = 3(x_{i+1} - x_{i+1}^-) \quad , \quad y_i'(1) = (y_{i+1} - y_{i+1}^-)3 \quad (6.2)$$

Using the 8 conds. the eight coefficients are determined.

$$x_i(t) = x_i + 3(x_i^+ - x_i)t + 3(x_i + x_{i+1}^- - 2x_i^+)t^2 + (x_{i+1} - x_i + 3(x_i^+ - x_{i+1}^-))t^3 \quad (7)$$

$$y_i(t) = y_i + 3(y_i^+ - y_i)t + 3(y_i + y_{i+1}^- - 2y_i^+)t^2 + (y_{i+1} - y_i + 3(y_i^+ - y_{i+1}^-))t^3 \quad (8)$$

(*) what it changes is the magnitude of the tangent vector to C_i at each end.

Determination of the coefficients: a 's and b 's 3

$$\begin{cases} X_i'(t) = a_1^{(i)} + 2a_2^{(i)}t + 3a_3^{(i)}t^2 \\ Y_i'(t) = b_1^{(i)} + 2b_2^{(i)}t + 3b_3^{(i)}t^2. \end{cases}$$

Then

$$\left. \begin{aligned} X_i'(0) &= 3(X_i^+ - X_i) \\ \text{and } X_i'(0) &= a_1^{(i)} \end{aligned} \right\} \Rightarrow \boxed{a_1^{(i)} = 3(X_i^+ - X_i)}$$

Similarly, $\boxed{b_1^{(i)} = 3(Y_i^+ - Y_i)}$

Also,

$$3(X_{i+1} - X_{i+1}^-) = X_i'(1) = \check{a}_1^{(i)} + 2\check{a}_2^{(i)} + 3\check{a}_3^{(i)}$$

and $X_{i+1} = X_i(1) = \check{a}_0^{(i)} + \check{a}_1^{(i)} + \check{a}_2^{(i)} + \check{a}_3^{(i)}$

then,
$$\begin{cases} 2\check{a}_2^{(i)} + 3\check{a}_3^{(i)} = 3(X_{i+1} - X_{i+1}^-) - \check{a}_1^{(i)} \\ \check{a}_2^{(i)} + \check{a}_3^{(i)} = X_{i+1} - \check{a}_0^{(i)} - \check{a}_1^{(i)} \end{cases}$$

Also, from interpolation we know

$$\boxed{\begin{aligned} \check{a}_0^{(i)} &= X_i(0) = X_i \\ \check{b}_0^{(i)} &= Y_i(0) = Y_i \end{aligned}}$$

Solving this system:

$$\left[\begin{array}{cc|c} a_2^{(i)} & a_3^{(i)} & \\ 1 & 1 & A \\ 2 & 3 & B \end{array} \right] \sim \left[\begin{array}{cc|c} 1 & 1 & A \\ 0 & 1 & B-2A \end{array} \right]$$

$$a_3^{(i)} = B - 2A = 3(x_{i+1} - x_{i+1}^-) - a_1^{(i)} - 2x_{i+1} + 2a_0^{(i)} + 2a_1^{(i)}$$

$$= \boxed{3x_{i+1}} - 3x_{i+1}^- + 3x_i^+ - \boxed{3x_i} + \boxed{2x_{i+1}} + \boxed{2x_i}$$

or

$$\boxed{a_3^{(i)} = 3(x_i^+ - x_{i+1}^-) + x_{i+1} - x_i}$$

And $a_2^{(i)} = A - a_3^{(i)}$

$$= x_{i+1} - a_0^{(i)} - a_1^{(i)} - a_3^{(i)}$$

$$= \cancel{x_{i+1}} - \cancel{x_i} - 3(x_i^+ - x_i) - 3(x_i^+ - x_{i+1}^-) - \cancel{x_{i+1}} + \cancel{x_i}$$

$$= -6x_i^+ + 3x_i + 3x_{i+1}^- = 3(x_i + x_{i+1}^- - 2x_i^+)$$

or

$$\boxed{a_2^{(i)} = 3(x_i + x_{i+1}^- - 2x_i^+)}$$

Similarly,

$$b_3^{(i)} = 3 (y_i^+ - y_{i+1}^-) + y_{i+1} - y_i$$

$$b_2^{(i)} = 3 (y_i + y_{i+1}^- - 2 y_i^+)$$

Summarizing given the data points:

Interpolation points: $(x_i, y_i), (x_{i+1}, y_{i+1})$

left guide point: (x_i^+, y_i^+)

Right guide point: (x_{i+1}^-, y_{i+1}^-)

We can construct cubic parametric polynomials:

$$\begin{aligned} x_i(t) &= a_0^{(i)} + a_1^{(i)}t + a_2^{(i)}t^2 + a_3^{(i)}t^3 \\ y_i(t) &= b_0^{(i)} + b_1^{(i)}t + b_2^{(i)}t^2 + b_3^{(i)}t^3 \end{aligned}, t \in [0, 1].$$

Interpolating the points: (x_i, y_i) and (x_{i+1}, y_{i+1})

and satisfying the eight conditions:

$$x_i(0) = x_i$$

$$x_i(1) = x_{i+1}$$

$$x_i'(0) = 3(x_i^+ - x_i)$$

$$x_i'(1) = 3(x_{i+1} - x_{i+1}^-)$$

$$y_i(0) = y_i$$

$$y_i(1) = y_{i+1}$$

$$y_i'(0) = 3(y_i^+ - y_i)$$

$$y_i'(1) = 3(y_{i+1} - y_{i+1}^-)$$

They are given by

$$x_i(t) = x_i + 3(x_i^+ - x_i)t + 3(x_i + x_{i+1}^- - 2x_i^+)t^2 + (x_{i+1} - x_i + 3(x_i^+ - x_{i+1}^-))t^3$$

$$y_i(t) = y_i + 3(y_i^+ - y_i)t + 3(y_i + y_{i+1}^- - 2y_i^+)t^2 + (y_{i+1} - y_i + 3(y_i^+ - y_{i+1}^-))t^3$$

Alternative Derivation of parametric Bezier curves
DIVIDED DIFFERENCES USING HERMITE
INTERPOLATION.

$$t_0 = 0 \quad X_i[t_0] = X_i(0)$$

$$X_i[t_0, t_1] = X_i'(0) \xrightarrow{t_0}$$

$$t_1 = 0 \quad X_i[t_1] = X_i(0)$$

$$X_i[t_1, t_2] = \frac{X_i(1) - X_i(0)}{1}$$

$$t_2 = 1 \quad X_i[t_2] = X_i(1)$$

$$X_i[t_2, t_3] = X_i'(1) \xrightarrow{1}$$

$$t_3 = 1 \quad X_i[t_3] = X_i(1)$$

Next column:

$$X_i[t_0, t_1, t_2] = \frac{X_i[t_1, t_2] - X_i[t_0, t_1]}{t_2 - t_0}$$

$$= \frac{X_i(1) - X_i(0) - X_i'(0)}{1}$$

$$X_i[t_1, t_2, t_3] = \frac{X_i[t_2, t_3] - X_i[t_1, t_2]}{t_3 - t_1}$$

$$= \frac{X_i'(1) - X_i(1) + X_i(0)}{1}$$

$$\begin{aligned}
 X[t_0, t_1, t_2, t_3] &= \frac{X_i[t_1, t_2, t_3] - X_i[t_0, t_1, t_2]}{t_3 - t_1 = 1} \\
 &= \frac{X_i'(1) - X_i(1) + X_i(0) - X_i(1) + X_i(0) + X_i'(0)}{1} \\
 &= X_i'(1) - 2X_i(1) + 2X_i(0) + X_i'(0).
 \end{aligned}$$

Now, using

$$X_i'(0) = 3(X_i^+ - X_i), \quad X_i'(1) = 3(X_{i+1} - X_{i+1}^-)$$

We obtain. and interpolation points.

$$\begin{aligned}
 X_i(t) &= X_i(0) + X_i'(0)t + (X_i(1) - X_i(0) - X_i'(0))t^2 \\
 &\quad + (X_i'(1) - 2(X_{i+1} - X_i) + X_i'(0))t^3(t-1)
 \end{aligned}$$

or

$$\begin{aligned}
 X_i(t) &= X_i + 3(X_i^+ - X_i)t + (X_{i+1} - X_i - 3(X_i^+ - X_i))t^2 \\
 &\quad - (X_i'(1) - 2(X_{i+1} - X_i) + X_i'(0))t^2 \\
 &\quad + (X_i'(1) - 2(X_{i+1} - X_i) + X_i'(0))t^3 \\
 &=
 \end{aligned}$$